Ahmed Yesuf **Nurye**

System Engineer @ Northvolt · Robotics Enthusiast

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Summary_

I'm currently pursuing my M.Sc. in Robotics and Automatic Control at Warsaw University of Technology. I'm a fast learner, possessing self-taught skills in Python, C++, MATLAB/Simulink, ROS, software design and testing, along with proficiency in Git and Linux OS. I'm deeply passionate about the development of intelligent systems, particularly in the fields of human-robot interaction and autonomous mobile robots perception, localization, mapping, and planning.

Education

Warsaw University of Technology

M.Sc. IN ROBOTICS AND AUTOMATIC CONTROL | CGPA: 4.81/5.0

- Advisor: prof. dr hab.inż. Elżbieta Jarzębowska.
- Thesis: Mobile Robot Navigation in a Dynamic Environment.

Addis Ababa Science and Technology University

B.Sc. in Electrical Engineering | CGPA: 3.96/4.0

• B.Sc. Project: Smart Irrigation System Powered by Dual Axis Solar Tracker.

Warsaw, Poland Oct. 2022 - Oct. 2024

Addis Ababa, Ethiopia

Oct. 2016 - Sep. 2021

Skills_____

Python, C++, MATLAB, Simulink, ROS, Gazebo, CoppeliaSim
Motion Planning, SLAM, Kinematic & Dynamic analysis, Multi-body systems, Control Theory, Machine Learning
Linux, Shell (Bash/sh), Git, 时 _E X, Microsoft Office
Excellent Communication, Time Management, Teamwork, Problem-solving, Presentation
English (CEFR - Level C1), Amharic (Native)

Industry_

Northvolt Gdańsk. Poland SYSTEM ENGINEER | MODEL-BASED DESIGN VERIFICATION AND VALIDATION ENGINEER Apr. 2024 - Present Maintenance of model, software and hardware in the loop software. · Develop test cases & perform unit testing for battery management system functions. Perform model-based verification and validation for battery management system functions. **New Era Research and Development Center** Addis Ababa, Ethiopia **ROBOTICS ENGINEER INTERN** Apr. 2021 - Jun. 2021 • Implemented various algorithms for mobile robot path planning (e.g., Bug1&2, Wavefront).

Teaching

Addis Ababa Science and Technology University

Electrical Measurement & Instrumentation (EEEg3153), Teaching assistant 2021

2022 Introduction to Control System (EEEg4155), Teaching and lab assistant

Projects_____

Development of Kinematic Analysis Tool Using Absolute Coordinates

WARSAW UNIVERSITY OF TECHNOLOGY CO-ADVISORS: PROF. JANUSZ FRĄCZEK & D.SC. MAREK WOJTYRA

- Developed a kinematic analysis tool using absolute coordinates for a general case planar multi-body system in MATLAB environment.
- Tested the implementation against results obtained from MSC Adams simulation software.

Six Degree of Freedom Serial Manipulator

Warsaw University of Technology | Advisor: Dr inż. Paweł Maciąg

- Derived the analytical solution of the inverse kinematics of the robot arm.
- Performed both task space (using interpolation) and joint space (using LSPB and quintic polynomial) trajectory planning.
- Tested implementation on the actual hardware for a pick and place task.

Warsaw, Poland

Oct. 2024 - Jan. 2024

Warsaw, Poland

Feb. 2022 - Jun. 2022

Controller Design Specification for a 6-DOF Serial Manipulator with a Two-State Gripper Endowed with Visual Perception

WARSAW UNIVERSITY OF TECHNOLOGY ADVISOR: PROF. DR HAB. INŻ. CEZARY ZIELIŃSKI

- Determined the internal structure of the agent and appropriate sampling rates of the agents' subsystems.
- Specified the general behavior of the virtual effectors and receptors.
- Defined the agents transition and terminal conditions governing its behaviour.
- Determined the structure of the FSM of the control subsystem invoking the defined behaviours.

Achievements & Volunteer Work

- 2024 Mr Tomaka's Scholarship, Warsaw University of Technology
- 2022 Banach Scholarship, NAWA Polish National Agency for Academic Exchange
- 2021 **Gold medal**, Graduated with the highest honer (rank: 1/450)
- 2019 Charity Affairs Committee, Served as core member of AASTU students union charity affairs committee Addis Ababa, Ethiopia

Feb. 2022 - Jun. 2022

Warsaw, Poland

Warsaw, Poland

Addis Ababa, Ethiopia

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